1. Introduction to wall-bounded turbulent flows

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Lecture 1, 21 August 2023 Les Houches School of Physics



Canonical wall-bounded flows



- Plane Couette flow
- Fully-developed channel flow of high aspect ratio
- Fully-developed pipe flow
- Boundary layer, flat plate, zero pressure gradient
- Ekman layers, Taylor-Couette flows, Rayleigh-Bénard convection, ...
- All flows turbulent (high Reynolds number) and free of history effects



Munson video

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Munson video

Internal versus external flows

- Internal flows:
 - Non-zero turbulent kinetic energy on centerline
 - Time sharing of large structures (Dean & Bradshaw 1976)
 - Channel flow: perimeter/area = 1/h (w >> 2h)
 - Pipe flow: perimeter/area = 2/R
- External boundary layer flow:
 - Laminar freestream
 - Intermittency
 - Sensitive to tripping condition



Corke, Guezennec and Nagib (1980)



Wu & Moin (2008)







Chung et al. (2015)

Osborne Reynolds' experiment



Transition to turbulent flow

- Most testing is done at low Reynolds number
- Many engineering applications are at high Reynolds number
- Most theories of turbulence only apply at high Reynolds number

Lab:
$$Re_{\tau} = 10^3, 10^4$$
 Applications: $Re_{\tau} = 10^4, 10^6$



Windpower Engineering Vestas V112

www.newairplane.com

Turbulent flows and Reynolds number

- Reynolds number critical parameter in laminar to turbulent transition
- Turbulence continues to evolve with increasing Reynolds number

$$Re = \frac{UL}{\nu} = \frac{\text{inertia force}}{\text{viscous force}} \sim \frac{L}{\nu/U} = \frac{\text{largest eddy size}}{\text{smallest eddy size}}$$

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$$Re_{\tau} = \underbrace{\delta}_{\nu/U_{\tau}} = \underbrace{\delta}_{\nu} \underbrace{u_{\tau}}_{v} = \underbrace{\delta}_{v} \underbrace{u_{\tau}}_{(\text{turbulence velocity scale})}_{(\text{turbulence velocity scale})}$$

$$(Re_{\tau} = Re^{+})$$

Turbulent flows and Reynolds number

- Reynolds number critical parameter in laminar to turbulent transition
- Turbulence continues to evolve with increasing Reynolds number



Delo, Kelso & Smits (2004)

Corke, Guezennec & Nagib (1980)

The usual scaling

	Inner coordinates	Outer coordinates	
Mean velocity	$U^+ = \frac{U}{u_\tau}$	$\frac{U_{\infty}-U}{u_{\tau}}$	$u_{\tau} = \sqrt{\tau_w/\rho}$
Fluctuations	$\overline{u^2}^+ = \frac{\overline{u'^2}}{u_\tau^2}$	$\overline{u^2}^+ = \frac{\overline{u'^2}}{u_\tau^2}$	
Wall distance	$y^+ = \frac{yu_\tau}{\nu}$	$\frac{y}{\delta} \text{ or } \frac{y}{R}$	$Re_{\tau} = \frac{\delta u_{\tau}}{\nu}$
	(viscous or inner scaling)	(outer scaling)	

• Dimensional analysis: $U = f(y, \tau_w, \mu, \rho, \delta)$



- Dimensional analysis: $U=f(y, au_w,\mu,
 ho,\delta)$
- Viscosity important near wall, but not important far from wall (at high Re_{τ})



- Dimensional analysis: $U = f(y, \tau_w, \mu, \rho, \phi)$
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Inner scaling:
$$\frac{U}{u_{\tau}} = f\left(\frac{yu_{\tau}}{\nu}\right)$$
, or $U^+ = f(y^+)$ $\left(u_{\tau} = \sqrt{\tau_w/\rho}\right)$



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, or $U^+ = f(y^+)$ $\left(u_{\tau} = \sqrt{\tau_w/\rho}\right)$
Outer scaling: $\frac{U_{\infty} - U}{u_{\tau}} = g\left(\frac{y}{\delta}\right)$



- Dimensional analysis: $U=f(y, au_w,\mu,
 ho,\delta)$
- Viscosity important near wall, but not important far from wall (at high Re_{τ})



Experiments and computations

Air at pressures up to 200 bar

Princeton Superpipe: $1000 \le Re_{\tau} \le 500,000$ HRTF: $2600 \le Re_{\tau} \le 72,500$





Princeton high Reynolds number facilities



Working fluid is air at pressures up to 200 bar

Superpipe



 $31 \times 10^3 \le Re_D \le 35 \times 10^6$ $10^3 \le Re_\tau \le 5 \times 10^5$

Superpipe



 $31 \times 10^3 \le Re_D \le 35 \times 10^6$ $10^3 \le Re_\tau \le 5 \times 10^5$

High Reynolds number test facility (HRTF)



High Reynolds number test facility (HRTF)





Data from Lee & Moser (2015)



Data from Lee & Moser (2015)





Inner scaling revisited at high Reynolds number

- Log-law was derived by matching gradients of ٠ velocity in the overlap region
- However, if we match velocity gradients and ٠ magnitudes in the overlap region, a power law can be derived: $U^{+} = C_1 \left(y^{+} \right)^{\gamma}$





Beverley McKeon



Mark Zagarola

Margit Vallikivi

Zagarola & Smits (1998) McKeon, Li, Jiang, Morrison & Smits (2004) Bailey, Vallikivi, Hultmark & Smits (2014)

Inner scaling revisited at high Reynolds number

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- However, if we match velocity gradients and magnitudes in the overlap region, a power law can be derived: $U^+ = C_1 (y^+)^{\gamma}$
- Experiments reveal that a power law joins the viscous sublayer to the log-law
- The log-law begins at y+ = 600
- It ends at $y/\delta = 0.12$
- Log-law only appears for $\text{Re}_{\tau} > 10,000$ (one octave), or 50,000 (one decade)



Zagarola & Smits (1998) McKeon, Li, Jiang, Morrison & Smits (2004) Bailey, Vallikivi, Hultmark & Smits (2014)

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- Log-law only appears for $\text{Re}_{\tau} > 10,000$ (one octave), or 50,000 (one decade)
- What about κ ?
- Best estimate for pipe flow $\kappa = 0.40 \pm 0.02$
- Other people find more precise values
- Can DNS help?



Zagarola & Smits (1998) McKeon, Li, Jiang, Morrison & Smits (2004) Bailey, Vallikivi, Hultmark & Smits (2014)





(will probably need DNS at much higher Reynolds number to be more precise)

DNS by Lee & Moser (2015)

- Dimensional analysis: $U = f(y, u_{\tau}, \mu, \rho, \delta)$ $\left(u_{\tau} = \sqrt{\tau_w/\rho}\right)$
- Assumes one velocity scale for inner and outer regions
- Experiments suggest both an inner scale (u_{τ}) and an outer scale (u_{ZS})
- Propose $u_{ZS}=\left(\delta^*/\delta\right)U_\infty$ (Zagarola & Smits 1997; 1998)
- In the outer region scale u_{ZS} works better than u_{τ} at lower Reynolds numbers



By integrating the velocity profile, we can obtain a friction factor/Reynolds number relationship:

Superpipe results



Pipe flow friction: the Moody Diagram



Two complementary experiments



McKeon et al. (2004)

• Dimensional analysis:
$$\overline{u_i u_j} = f(y, u_\tau, \mu, \rho, \delta)$$
 $\left(u_\tau = \sqrt{\tau_w/\rho}\right)$

• Using the inner/outer overlap argument:

 $\begin{array}{ll} \text{Match amplitudes} & \overline{u_i u_j} = \text{ constant} \\ & \text{Match gradients} & \overline{u_i u_j} = B_i - A_i \ln(y/\delta) \\ & \text{Match gradients and amplitudes} & \overline{u_i u_j} = C_i (y/\delta)^{\gamma_i} \end{array}$
• Dimensional analysis:
$$\overline{u_i u_j} = f(y, u_{ au}, \mu,
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- As we shall see, different components of the stress tensor follow different scaling in the overlap region
- For example, $\overline{u^2}/u_{ au}^2$ follows a logarithmic variation, while $\overline{v^2}/u_{ au}^2$ is a constant
- No power law behavior has been seen







Scaling the turbulence: the Attached Eddy Hypothesis



<u>Townsend</u>: "In other words, the velocity fields of the main eddies, regarded as persistent, organized flow patterns, extend to the wall and, in a sense, they are attached to the wall."



Scaling the turbulence: the Attached Eddy Hypothesis



<u>Perry</u>: In this theory, wall turbulence is considered to consist of a 'forest' of randomly positioned horseshoe, hairpin or Λ -shaped vortices that lean in the streamwise direction and have their legs extending to the wall.

Townsend: "In other words, the velocity fields of the

main eddies, regarded as persistent, organized flow patterns, extend to the wall and, in a sense, they are

attached to the wall."







Perry & Chong (1982)

Direction of fle Townsend (1976)



Townsend/Perry Attached Eddy Model

- The model is inviscid (high Reynolds number), and considers a superposition of geometrically selfsimilar, attached eddies
- The eddies cover a wide range of scales, but each scale is proportional to the distance from the wall
- The eddies have the same characteristic velocity scale
- At high enough Reynolds number, the model is designed to give $-\overline{uv}/u_{ au}^2=1$
- Model applies in the constant stress (logarithmic) region

At high Reynolds number, the model then predicts:

$$\overline{\frac{u^2}{u_\tau^2}} = B_1 - A_1 \ln\left(\frac{y}{\delta}\right)$$
$$\overline{\frac{v^2}{u_\tau^2}} = A_2$$
$$\overline{\frac{w^2}{u_\tau^2}} = B_3 - A_3 \ln\left(\frac{y}{\delta}\right)$$

Need accurate measurements at high Reynolds number

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$$\frac{\overline{v^2}}{u_\tau^2} = A_2$$

$$\frac{\overline{w^2}}{u_\tau^2} = B_3 - A_3 \ln\left(\frac{y}{\delta}\right)$$

Nano-Scale Thermal Anemometry Probe (NSTAP)



- MEMS construction
- Free-standing Pt ribbon
- 0.1 x 2 µm cross-section
- 30 or 60 µm sensing length
- Frequency response > 150kHz



Marcus Hultmark





Bailey et al. (2010) Vallikivi , Bailey, Hultmark & Smits (2011) Vallikivi & Smits (2014) Hutchins, Monty, Hultmark, Smits (2015)

Superpipe turbulence data (NSTAP)

• NSTAP measurements established, unambiguously for the first time, the log law in the turbulence

$$\overline{u^2}^+ = 1.61 - 1.25 \ln\left(\frac{y}{\delta}\right)$$

- This is a key result in the Attached Eddy Model of Townsend/Perry
- Holds for pipes and boundary layers, with the same slope (A₁=-1.25)



Hultmark , Vallikivi, Bailey & Smits (2012) Marusic, Monty, Hultmark & Smits (2013) Vallikivi, Hultmark & Smits (2015)

Boundary layer vs. pipe flow



Hultmark, Vallikivi, Bailey & Smits (2013) Vallikivi, Hultmark & Smits (2015)

A universal log law for turbulence?



Marusic, Monty, Hultmark & Smits (2012)

NSTAP measurements in the Melbourne tunnel

Thick boundary layer, small $\ell^+ = \ell/\eta_v$ $2.4 \leq \ell^+ \leq 3.5$



Samie , Marusic, Hutchins, Fan, Fu, Hultmark & Smits (2018)



Growth of the inner peak



How far can we get analytically? How about a Taylor series expansion for small y^+ :

$$(U+u)^{+} = a_1 + b_1 y^{+} + c_1 y^{+2} + d_1 y^{+3} + O(y^{+4})$$

$$all = f_{u^2} y^{+2} \quad (y^+ \to 0)$$

$$f_{u^2} \ (= \overline{b_1^2}) \quad {}^{\longrightarrow} \ {
m find using DNS}$$

Smits, Hultmark, Lee, Pirozzoli & Wu (2021)

Channel flow DNS

 $Re_{\tau} = 544, 1000, 1995, 5186$



Channel flow DNS



$$u_{p}^{2^{+}} = 46f_{u^{2}}$$

(see also Chen & Sreenivasan 2021)

Experiments at high Reynolds number



Data collapse for 0<y⁺<50

What does it mean?



$$f_{u^2} = \overline{\left(\frac{\partial u^+}{\partial y^+}\right)_w^2} = \frac{\overline{\tau'_{wx}^2}}{\tau_w^2}$$

- Wall stress scaling
- Modulation and superimposition of the near-wall motions by large outer scale motions
- Determines scaling for entire nearwall region
 - Marusic et al. (2010) Örlü & Schlatter (2011) Mathis et al. (2013) Agostini & Leschziner (2016, 2018) Yang & Lozano-Duráan (2013) Lee & Moser (2019)

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Summary

- Pipe, channel and boundary layer flows obey similar scaling
- Some differences exist, primarily in the nature of the outer-layer eddy structure

Mean flow

- Inner and outer scaling
- Log-law widely accepted but only appears at high Reynolds number
- Power law blends viscous sublayer to log law
- Outer layer has two velocity scales at low Reynolds number, u_τ and u_{ZS}

Turbulence

- Outer scaling works well
- In overlap region, log-law in u² and w², but v² and –uv are constant
- Near wall intensity in u² grows with Reynolds number due to modulation and superimposition of the near-wall motions by large outer scale motions
- Wall stress determines scaling for entire near-wall region
- Outer peak in u² appears at high Reynolds number

Summary

Reynolds number scaling

- Need Re_{τ} > 10,000 to understand high Reynolds number behavior
- Experiments were the only way to get high Reynolds numbers, but DNS is coming along (quickly)

Summary

Reynolds number scaling

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Effort ~ $O(Re_{\tau}^{3})$ for IHT

Coleman & Sandberg (2010)



Computing turbulent wall-bounded flows

Direct Numerical Simulations (DNS)

- 3D, time-resolved
- No model: captures all scales
- Accuracy limited only by numerical scheme, grid size/spacing, domain size
- Expensive, slow
- Cost > O(Re³)
- Research tool

Large Eddy Simulations (LES)

- 3D, time-resolved
- Model sub-grid scales
- Accuracy limited by model, grid size/spacing, domain size, wall treatment
- Medium expensive, medium fast
- Cost (wall-modeled) ~O(Re)
- Research tool transitioning to a design tool (Goc et al. 2021)

Reynolds-Averaged Navier-Stokes (RANS)

- 3D, steady or quasi-steady
- Model all turbulent scales (Boussinesq)
- Accuracy limited by model, numerical scheme, grid size/spacing, wall-functions, etc. (ERCOFTAC)
- Cheap, fast
- Design tool for industry





Wu & Moin (2009)



Direct Numerical Simulations

Very useful for examining near-wall behavior, although DNS Reynolds numbers) the outer layer influence is muted

Captures scaling of spanwise and wallnormal stresses)

In-depth spectral analysis (e.g., 2D spectra, true wavenumber spectra)

Great for testing spatial and temporal content

Not very useful for examining high Reynolds number behavior (e.g., log law constants, log-law in streamwise stress, inner peak, outer peak) Need $\text{Re}_{\tau} > 10,000$ to understand high Reynolds number behavior

DNS of boundary layer flow 2.1×10^8 points, Re_t max 460



Wu & Moin (2009)

Effort ~ $O(Re_{\tau}^{3})$ for IHT

$Re_{\tau} = 170, 300, 650 \text{ (Spalart 1988)}$

First DNS of a wall-boundary flow Time evolution of channel flow with periodic boundary conditions Robinson (1991) Re_{τ} = 300 case





3.2 to 9.4 x 10⁶ points

$Re_{\tau} = 2000$ (Hoyas & Jiménez 2011)



Direct Numerical Simulations

DNS of channel flow Channel flow ($Re_{\tau} = 10,000$) 100,000 Domain $8\pi h \times 2h \times 3\pi h$ Pipe flow ($\text{Re}_{\tau} = 6000$) 10,000 Domain $10-15\pi R$ Boundary layer ($\text{Re}_{\tau} = 2000$) Re_{τ} Transition 1,000 Typical resolution near the wall $\Delta x^+ = 10$, $\Delta y^{+} = 0.2, \Delta z^{+} = 5$ 100 2010 1980 1990 2000

Need $Re_{\tau} > 10,000$ to understand high Reynolds number behavior

2020

year

2030

Large Eddy Simulations

Example: channel flow Domain $4\pi h \times 2h \times 2\pi h$ Wall-resolved (WRLES):

Turbulence resolved all the way to the wall, with typical resolution near the wall $\Delta x^+ = 15$, $\Delta y^+ = ??$, $\Delta z^+ = 20$

Computational cost ??

Wall-modeled (WMLES):

Turbulence not resolved for y/ δ < 0.1-0.2 For y/ δ < 0.1-0.2, use a wall-stress model, or a RANS model

ABL solvers typically impose a log-law for the mean flow, since the first grid point is typically already in the log region Computational cost ?? Need to choose a filter function with length scale Δ Many choices: box, spectral, Gaussian, etc. Need to choose a sub-grid scale model Example, dynamic Smagorinsky



Large Eddy Simulation milestones/people

Smagorinsky (1963) atmospheric flows Deardorff (1970) channel flow Schumann (1975) Leonard (1975) Kim & Moin (1979) Piomelli (1989) - wall modeling Spalart et al. (1997) – detached eddy simulation











Ulrich Schumann



Anthony Leonard



John Kim

Parviz Moin



Ugo Piomelli



Philippe Spalart

Large Eddy Simulations

Consider the unsteady, incompressible momentum equation for turbulent flow

$$\frac{\partial u_i}{\partial t} + \frac{\partial u_i u_j}{\partial x_j} = -\frac{1}{\rho} \frac{\partial p}{\partial x_i} + \nu \frac{\partial^2 u_i}{\partial x_i \partial x_j}$$

Decompose velocity in large-scale component + small-scale component: $u_i = \overline{u_i} + u_i'$

Need to define a filter function (can be different in all three directions). The filter width Δ is typically 2x the grid spacing. Filtered equation: $\partial \bar{u} = \partial \bar{u} = 1$, $\partial \bar{v} = -\partial \bar{v}$, $\partial \bar{z} = -\partial \bar{z}$

$$\frac{\partial u_i}{\partial t} + \frac{\partial u_i u_j}{\partial x_j} = -\frac{1}{\rho} \frac{\partial p}{\partial x_i} + 2\nu \frac{\partial S_{ij}}{\partial x_j} - \frac{\partial \tau_{ij}}{\partial x_j}$$

$$\begin{cases} L_{ij} = \overline{u}_i \overline{u}_j - \overline{u}_i \overline{u}_j \\ C_{ij} = \overline{u}_i u'_j + \overline{u}_j u'_j \\ R_{ij} = \overline{u'_i u'_j} \end{cases}$$

Leonard stresses (interactions among large scales)

Backscatter stresses (interactions between large and small scales)

Reynolds stress-like term (interactions among sub-filter scales)

 τ_{ij} needs to be modeled

Basically, an eddy viscosity approach: $\tau_{ij} = -\nu_T \bar{S}_{ij}$ $\bar{S}_{ij} = \frac{1}{2} \left(\frac{\partial \bar{u}_i}{\partial x_j} + \frac{\partial \bar{u}_j}{\partial x_i} \right)$

Small-scale

$$\begin{array}{c} \text{Production} = -\overline{u'_i u'_j} \, \bar{S}_{ij} = 2\nu_T \, \bar{S}_{ij} \bar{S}_{ij} \\ \text{Dissipation} = c_1 (\overline{u'_i u'_i})^{3/2} / \ell \end{array}$$

$$\begin{array}{c} \nu_T = \ell^2 (\overline{u'_i u'_j})^{1/2} \quad \text{(production = dissipation)} \\ \text{Dissipation} = c_1 (\overline{u'_i u'_i})^{3/2} / \ell \end{array}$$

Here, $\,\ell\,$ is a length scale representative of a SGS eddy, so $\,\ell\propto\Delta\,$

Hence,
$$\nu_T = C' \Delta^2 \sqrt{2\bar{S}_{ij}\bar{S}_{ij}} = C \Delta^2 |\bar{S}_{ij}|$$
 Smagorinsky-Lilly SGS model

Piomelli:
$$\ell_{PFM} = C_S \left[1 - \exp\left(-y^{+3}/A^{+3}\right) \right]^{1/2} \left(\Delta_1 \Delta_2 \Delta_3 \right)^{1/3}$$

which ensures the proper behavior for the SGS Reynolds stress τ_{12} near the wall $(\tau_{12} \sim y^{+3})$

Comparing turbulence models



At present, RANS is the best we can do for industrial flows

Comparing turbulence models



At present, RANS is the best we can do for industrial flows

Reynolds-Averaged Navier-Stokes

- RANS models use Reynolds decomposition to derive equations for the mean momentum and the time-averaged turbulent stresses $\overline{u^2}$, $\overline{v^2}$, $\overline{w^2}$, $-\overline{uv}$, ...
- Essentially a steady flow model (although unsteady versions exist (URANS)
- Many different versions are in use
- All versions use the Boussinesq approximation where higher order quantities are modeled as gradients of lower order quantities (eddy viscosity models)
- All use the isotropic estimate for the dissipation

Two equation models

- One equation for turbulence
 - e.g., TKE (k-ε), vorticity (k, ω)
- One equation for length scale
 - Dissipation length scale L_{ϵ}

Reynolds stress models

- One equation for each turbulent stress component (up to 6 equations)
- One equation for length scale
 - Dissipation length scale L_{ϵ}
• For steady (or quasi-steady) flow, Reynolds decomposition gives the following mean momentum equations:

$$\begin{split} U\frac{\partial U}{\partial x} + V\frac{\partial U}{\partial y} + W\frac{\partial U}{\partial z} &= -\frac{1}{\rho}\frac{\partial p}{\partial x} - \left(\frac{\partial \overline{u^2}}{\partial x} + \frac{\partial \overline{u}\overline{w}}{\partial y} + \frac{\partial \overline{u}\overline{w}}{\partial z}\right) + \nu\nabla^2 U \\ U\frac{\partial V}{\partial x} + V\frac{\partial V}{\partial y} + W\frac{\partial V}{\partial z} &= -\frac{1}{\rho}\frac{\partial p}{\partial y} - \left(\frac{\partial \overline{u}\overline{v}}{\partial x} + \frac{\partial \overline{v^2}}{\partial y} + \frac{\partial \overline{v}\overline{w}}{\partial z}\right) + \nu\nabla^2 V \\ U\frac{\partial W}{\partial x} + V\frac{\partial W}{\partial y} + W\frac{\partial W}{\partial z} &= -\frac{1}{\rho}\frac{\partial p}{\partial z} - \left(\frac{\partial \overline{u}\overline{w}}{\partial x} + \frac{\partial \overline{v}\overline{w}}{\partial y} + \frac{\partial \overline{w^2}}{\partial z}\right) + \nu\nabla^2 W \\ \text{That is} \qquad U_j\frac{\partial U_i}{\partial x_j} = \frac{1}{\rho}\frac{\partial}{\partial x_j}\left(-p\delta_{ij} + 2\mu S_{ij}\right) - \rho\overline{u_iu_j}\right) \\ \tau_{ij} \text{ needs to be modeled} \end{split}$$

Boundary layer equations



RANS: turbulent stress equations

• For steady (or quasi-steady) flow, Reynolds decomposition gives the following turbulent stress equation:

$$\frac{D\left(\frac{1}{2}\overline{u^{2}}\right)}{Dt} = -\frac{1}{\rho}\frac{\partial\overline{p'u}}{\partial x} + \frac{1}{\rho}\overline{p'\frac{\partial u}{\partial x}} + \nu\overline{u}\overline{\nabla^{2}u} - \left(\overline{u^{2}}\frac{\partial U}{\partial x} + \overline{uv}\frac{\partial U}{\partial y} + \overline{uw}\frac{\partial U}{\partial z}\right) - \frac{1}{2}\left(\frac{\partial\overline{u^{3}}}{\partial x} + \frac{\partial\overline{u^{2}v}}{\partial y} + \frac{\partial\overline{u^{2}w}}{\partial z}\right)$$
Transport term
(sums to zero across the energy by work done in transporting fluid through regions of changing pressure gradient)
$$Tendency to isotropy (transfer of turbulent energy to other components)$$

Similar equations can be derived for the other stress components

Turbulence Kinetic Energy (TKE) equations

• Summing the normal stress equations gives the TKE or k-equation: $k = \frac{1}{2}\overline{q^2} = \frac{1}{2}\overline{u_i u_i} = \frac{1}{2}(\overline{u^2} + \overline{v^2} + \overline{w^2})$

Mean advection
$$\frac{D\left(\frac{1}{2}\overline{q^2}\right)}{Dt} = -\frac{\partial}{\partial x_j}\left(\frac{\overline{p'u_j}}{\rho} + \frac{1}{2}\overline{u_jq^2}\right) - \overline{u_iu_j}\frac{\partial U_i}{\partial x_j} + \nu \overline{u_i}\frac{\partial^2 u_j}{\partial x_j^2}$$

Pressure diffusion (net loss of turbulent energy by work done in transporting fluid through regions of changing pressure gradient)

> Turbulent advection (rate of transport of TKE by the turbulence)

Production (energy extracted from the mean flow by the turbulence) Dissipation (closely equal to the dissipation of mean flow kinetic energy into heat)

All terms on the RHS need to be modeled in terms of U_i and $\frac{1}{2}q^2$

The Boussinesq approximation

• Boussinesq's hypothesis is that the turbulent stresses are related to the mean velocity gradients in a way that is similar to the way viscous stresses are related to the complete velocity gradients.

Incompressible form only
$$U_{j}\frac{\partial U_{i}}{\partial x_{j}} = \frac{1}{\rho}\frac{\partial}{\partial x_{j}}\left(-p\delta_{ij}+2\mu S_{ij}-\rho\overline{u_{i}u_{j}}\right) \qquad S_{ij} = \frac{1}{2}\left(\frac{\partial U_{i}}{\partial x_{j}}+\frac{\partial U_{j}}{\partial x_{i}}\right)$$
Definition of eddy viscosity
$$\overline{u_{i}u_{j}} = 2\nu_{t}S_{ij} - \frac{2}{3}k\delta_{ij} \qquad k = \frac{1}{2}\overline{u_{i}u_{i}} = \frac{1}{2}(\overline{u^{2}}+\overline{v^{2}}+\overline{w^{2}})$$
2D example:
$$-\overline{uv} = \nu_{t}\frac{\partial U}{\partial y} \qquad \text{Prandtl's eddy viscosity}$$
Definition of length scale
$$\nu_{t} \equiv \sqrt{k}\ell$$
2D example:
$$-\overline{uv} = \ell_{m}^{2}\frac{\partial U}{\partial y} \left|\frac{\partial U}{\partial y}\right| \qquad (\text{assuming } \overline{uv} \propto \overline{u^{2}}) \qquad \text{Prandtl's mixing length}$$
The underlying assumption is that ν_{t} or ℓ behave more simply than $\overline{u_{i}u_{j}}$

• Boussinesq's hypothesis is that the turbulent stresses are related to the mean velocity gradients in a way that is similar to the way viscous stresses are related to the complete velocity gradients.

Definition of length scale
$$\nu_t \equiv \sqrt{k\ell}$$

2D example: $-\overline{uv} = \ell_m^2 \frac{\partial U}{\partial y} \left| \frac{\partial U}{\partial y} \right|$ (assuming $\overline{uv} \propto \overline{u^2}$) Prandtl's mixing length
Constant stress region: $-\overline{uv} = u_\tau^2 = \ell_m^2 \frac{\partial U}{\partial y} \left| \frac{\partial U}{\partial y} \right|$
Hence: $\frac{\partial U}{\partial y} = \frac{u_\tau}{\ell_m}$
Log law: $\frac{\partial U}{\partial y} = \frac{u_\tau}{\kappa y}$ $\ell_m = \kappa y$
 $\ell_m = \kappa y$
 $\ell_m = \kappa y$

• Use the Boussinesq approximation to model the TKE equation in terms of q:

$$\frac{D\left(\frac{1}{2}\overline{q^2}\right)}{Dt} = -\frac{\partial}{\partial x_j}\left(\frac{\overline{p'u_j}}{\rho} + \frac{1}{2}\overline{u_jq^2}\right) - \overline{u_iu_j}\frac{\partial U_i}{\partial x_j} + \nu \overline{u_i}\frac{\partial^2 u_i}{\partial x_j^2}$$

For high Reynolds numbers

$$\frac{Dk}{Dt} = \frac{\partial}{\partial x_j} \left(\frac{\nu_t}{\sigma_k} \frac{\partial k}{\partial x_j} \right) + \nu_t \left(\frac{\partial U_i}{\partial x_j} + \frac{\partial U_j}{\partial x_i} \right) \frac{\partial U_i}{\partial x_j} - \varepsilon$$

$$\frac{D\varepsilon}{Dt} = \frac{\partial}{\partial x_j} \left(\frac{\nu_t}{\sigma_\varepsilon} \frac{\partial \varepsilon}{\partial x_j} \right) + C_1 \nu_t \frac{\varepsilon}{k} \left(\frac{\partial U_i}{\partial x_j} + \frac{\partial U_j}{\partial x_i} \right) \frac{\partial U_i}{\partial x_j} - C_2 \frac{\varepsilon^2}{k}$$

$$\nu_t = C_\mu k^2 / \varepsilon \qquad \nu_t \equiv \sqrt{k} \ell$$

$$C_\mu = 0.09, \quad C_1 = 1.44, \quad C_2 = 1.92, \quad \sigma_k = 1.00, \quad \sigma_\varepsilon = 1.3$$







Launder & Spalding (1974)

For low Reynolds numbers (near the wall)

$$\frac{Dk}{Dt} = \frac{\partial}{\partial x_j} \left(\left(\frac{\nu_t}{\sigma_k} + \nu \right) \frac{\partial k}{\partial x_j} \right) + \nu_t \left(\frac{\partial U_i}{\partial x_j} + \frac{\partial U_j}{\partial x_i} \right) \frac{\partial U_i}{\partial x_j} - 2\nu \left(\frac{\partial k^{1/2}}{\partial x_j} \right) - \varepsilon$$

Introduced for computational reasons

$$\frac{D\varepsilon}{Dt} = \frac{\partial}{\partial x_j} \left(\left(\frac{\nu_t}{\sigma_{\varepsilon}} + \nu \right) \frac{\partial \varepsilon}{\partial x_j} \right) + C_1 \nu_t \frac{\varepsilon}{k} \left(\frac{\partial U_i}{\partial x_j} + \frac{\partial U_j}{\partial x_i} \right) \frac{\partial U_i}{\partial x_j} - C_2 \frac{\varepsilon^2}{k} - 2.0\nu \nu_t \left(\frac{\partial^2 U_i}{\partial x_i \partial x_l} \right)^2 \right)$$

Introduced to make constrain k near the wall

$$C_{\mu} = C_{\mu\infty} \exp\left[-2.5/(1+R_t/50)\right], \quad C_1 = 1.44, \quad C_2 = C_{2\infty} \left[1.0 - 0.3 \exp(-R_t^2)\right], \quad \sigma_k = 1.00, \quad \sigma_{\varepsilon} = 1.3$$

$$(R_t = k^2/\nu\varepsilon \sim \nu_t/\nu)$$

Launder & Spalding (1974)

Dissipation modeling

• RANS models the dissipation using the isotropic results as a basis:

RANS:
$$\begin{array}{c} \nu_t = C_\mu k^2/\varepsilon \\ \nu_t \equiv \sqrt{k}\ell \end{array} \right\} \ \varepsilon = C_\mu \frac{k^{3/2}}{\ell} \label{eq:range}$$



For high Reynolds numbers (large scale separation):

 $arepsilon = rac{q^3}{\Lambda}$

where q and Λ are the velocity and length scales characteristic of the energy containing motions

- Need the energy containing motions to be independent of the boundary conditions
- The flow must be in a state where the inertial region is fully established
- The ϵ -equation is actually a length scale equation





Andrey Kolmogorov

George Batchelor



Energy budget for k, $Re_{\tau} = 5200$

$$0 = -2\overline{u}\overline{v}\frac{dU}{dy} - \frac{d\overline{k}\overline{v}}{dy} + \nu\frac{d^2k}{dy^2} + 0 + \frac{2}{\rho}\frac{d\overline{p'v}}{dy} - \epsilon_k$$

0 = production + turbulent transport + viscous transport + pressure strain + pressure transport + dissipation



Data from Lee & Moser (2015)

Energy budget for k, $Re_{\tau} = 5200$

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0 = production + turbulent transport + viscous transport + pressure strain + pressure transport + dissipation



Data from Lee & Moser (2015)

Turbulence kinetic energy production



Smits et al. (2018)

Summary: RANS methods

- Fast, stable, widely available commercially
- Industry standard design tool
- Ansys Fluent, OpenFOAM, SimFlow, Autodesk, FUN3D
- Many varieties available, tuned to specific flows (e.g., airfoils)
 - Spalart-Almares: transport equation for eddy viscosity (one-equation model tuned to airfoil flows)
 - k- ω : transport equations for k and $\omega~(\propto arepsilon/k)$ -- better near the wall than ~k-arepsilon
 - Menter Shear Stress Transport (SST): switches from k– ω near the wall to k- ϵ away from the wall to get the best of both worlds
 - SSG-LRR: full Reynolds stress model using the Launder-Reece-Rodi pressure-strain model near the wall and the Speziale-Sarkar-Gatski model away from the wall
 - Etc.
- No method is very good at predicting separation on smoothly varying surfaces
- If there is defined separation point, then DES methods preferred
- ERCOFTAC, NASA, CFD Online, OpenFOAM, etc.
- Machine learning

See also https://www.youtube.com/watch?v=AgvjPPzy64I&ab_channel=SteveBrunton

Example: RANS methods



Vissoneau, Deng, Gilmineau, Ding, Smits (2022)

Example: RANS methods



Summary

- It is now obvious that fundamental studies of turbulence must be performed as a partnership between experiment and DNS
- Some questions can still only be answered by experiment
- Some questions can only be answered by DNS
- For canonical flows, DNS will very soon provide the necessary information for future understanding, instead of experiment

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- Beyond canonical flows:
 - Subsonic: pressure gradient, curvature, divergence, sudden perturbations ...
 - High Mach number: heat transfer, chemistry, reacting flows

Summary

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- Beyond canonical flows:
 - Subsonic: pressure gradient, curvature, divergence, sudden perturbations ...
 - High Mach number: supersonic and hypersonic flows, shock-wave boundary layer interactions....

Questions?

